

Landscape metrics as a framework to measure the effect of landscape structure on the spread of invasive insect species

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Abstract

Context With accelerated land-use change throughout the world, increased understanding of the relative effects of landscape composition and configuration on biological system and bioinvasion in particular, is needed to design effective management strategies. However, this topic is poorly understood in part because empirical studies often fail to account for large gradients of habitat complexity and offer insufficient or even no replication across habitats.

Objectives The aim of this study was to disentangle the independent and interactive effects of landscape composition and landscape configuration on the establishment and spread of invasive insect species.

Methods We explore a spatially-explicit, mechanistic modeling framework that allows for systematic investigation of the impact of changes in landscape composition and landscape configuration on establishment and spread of invasive insect species.

Landscape metrics are used as an indicators of invasive insect establishment and spread.

Results We showed that the presence of an Allee effect leads to a balance between the effectiveness of spread and invasion success. Spread is maximized at an intermediate dispersal level and inhibited at both low and high levels of dispersal. The landscape, by either increasing or mitigating the dispersal abilities of a species, can lead to a rate of spread under a dispersal threshold for which density and spread is at the highest.

Conclusion Our study proposes that change in landscape structure is an additional explanation of the highly variable spread dynamics observed in natural and anthropogenic landscapes. Consequently, a landscape-scale perspective could significantly improve spread risk assessment and the design of control or containment strategies.

Keywords Invasive insects · Heterogeneous landscape · Landscape metrics · Population dynamics · Invasive spread · Spatially-explicit stochastic models

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Introduction

Throughout the world, habitat fragmentation and land-use change are among the most critical threats to biodiversity and ecosystems services (Millennium Ecosystem Assessment 2005; Cardinale et al. 2012). Both processes result in highly heterogeneous

landscapes exhibiting differing composition (habitat types and proportion) and configuration (spatial arrangement of habitat types) (Fahrig et al. 2011). Advances in theoretical and empirical approaches to the analysis of range expansion of invasive species have highlighted the importance of such spatial heterogeneity as a critical factor that can influence the invasion process (e.g. Hastings et al. 2005; Bradley 2010; Vilà and Ibáñez 2011; Betts et al. 2014). By interacting with the distribution of invasive species, levels of spatial heterogeneity can either promote the establishment and spread of such species (With 2002; La Morgia et al. 2011; Thies et al. 2011) or, alternatively, can act as a barrier to spread (Jules et al. 2002; Mundt et al. 2011) or host colonization (Zhang and Schlyter 2004). However, it is not fully understood why some new populations spread rapidly across the landscape while others spread slowly or not at all. Whether the variability observed in nature or in experimental ensembles might be accounted for by systematic differences between landscape structures remains an open research question (Richter et al. 2013; Sutherland et al. 2013; Meier et al. 2014).

Research on landscape-level effects on the establishment and spread of invasive species has focused predominantly on the contribution of natural and semi-natural habitat types surrounding urban, forest and agricultural ecosystems. Human based land-use promotes habitat disturbance and human assisted dispersal that can increase propagule pressure and promote the successful establishment and spread of an invading species (Pyšek and Richardson 2010; González-Moreno et al. 2013). For example, the urban landscape supports a diverse fauna ranging from native species to opportunistic species (both native and invasive) which exploit modified habitats (Garden et al. 2006). In contrast, modern methods in agricultural and plantation forestry ecosystems, have generated monocultures that are continuous in their extent and dominated by few crop species, leading to homogenized landscapes (Margosian et al. 2009). Landscape simplification increases the concentration of suitable resources that are available to particular invasive species (Tschardt et al. 2012; Rigot et al. 2014; Jonsson et al. 2015) and can reduce the number of habitat types that support invasive species' natural enemies (Chaplin-Kramer et al. 2011; Cardinale et al. 2012). Furthermore, the fragmentation of wild-land

habitat resulting from agricultural and urban development also affects the spread of invasive species (Harper et al. 2005; La Morgia et al. 2011; González-Moreno et al. 2014). Urban forests and parklands represent an increasing percentage of our remaining near-natural habitats. Because of their proximity to sites of introduction and their (often) large ratio of edge to interior habitat, they are prime habitat for introduced plant and animal species which can then spread into less urbanised areas (Martin et al. 2008). Landscape disturbance features such as hiking trails or roads can also promote invasion spread, in part by creating disturbed edges where invasive species can easily establish (Christen and Matlack 2006).

Synthesis of research across multiple taxa and habitat types offers strong evidence for landscape composition shaping the establishment and spread of an invasive species (e.g. Tschardt et al. 2012; Robledo-Arnuncio et al. 2014). Empirical studies are strongly supported by simulation models showing that the local density of invasive species is determined not only by local habitat quality, but also by the spatial structure of the habitat in the surrounding landscape (With 2002, 2004). Understanding the effect of the existing distribution of suitable/unsuitable habitat on the establishment and spread of invasive species is therefore critical for planning strategies to eradicate or contain an invasive species. However, the outcome of such spatial analysis remains limited by our ability to carry out a quantitative synthesis of landscape effects on the spread of a species. In particular, empirical studies often fail to account for large gradients of habitat complexity (e.g. patch size, shape, juxtaposition, inter-patch connectivity or habitat aggregation) and offer insufficient or even no replication across habitat. This deficiency is in part because of an unavoidable trade-off between spatial scope, sampling intensity and accuracy (Robledo-Arnuncio et al. 2014).

Spatially-explicit models, on the other hand, have provided a good basis for generating replicated landscape patterns with partially controllable spatial properties (With 2004). These models traditionally focus on the effect of a limited number of landscape attributes, such as habitat density or patch connectivity (With 2002; Seibert-Cuvillier et al. 2008; Smith et al. 2014; Morel-Journel et al. 2015), where connectivity is classically defined as the degree to which landscape features facilitate or impede the rate of

movement of species between habitat patches. Depending on the species considered, these different landscape features have been shown to modify dispersal rates between habitat patches (Calabrese and Fagan 2004) or the pattern of dispersion (Jonsen and Taylor 2000). Theoretical studies, such as that by Hanski and Gaggiotti (2004) suggest that as connectivity increases, it facilitates the formation of a metapopulation which can increase the persistence of local populations through source-sink dynamics. On the other hand, Smith et al. (2014) and Morel-Journel et al. (2015) suggested that increasing connectivity during dispersal allows more effective spread, but simultaneously can decrease population density at the source, which can accentuate demographic stochasticity and Allee effects. Although there is a substantial literature on demographic analysis of invasive populations that helps shed light on specific life-history traits contributing to invasion, only a minority of spatially-explicit models pose demographic processes as essential to a general understanding of the invasion process. Nevertheless, many studies report that the magnitude and direction of landscape effects on each species depends on that species life-history sensitivities to environmental disturbance as well as its dispersal abilities (Guisan and Thuiller 2005; Huntley et al. 2010; Schurr et al. 2012; Robledo-Arnuncio et al. 2014). Clearly, there is a need for more integrative approaches that link demographic processes and dispersal strategies to the landscape to better understand the consequences of increasing anthropogenically driven land-use change, and global environmental and climatic change on species spread (Bocedi et al. 2014; Robledo-Arnuncio et al. 2014; Wang and Jackson 2014).

The primary aim of this study was to disentangle the independent and interactive effects of landscape composition and landscape configuration on the establishment and spread of invasive insect species. Critical to this effort is the development of a spatially-explicit, mechanistic model to forecast the spread of species in relation to landscape structure. We use the available modelling platform, MDiG (Pitt 2008; Pitt et al. 2009) to examine how the rate of range expansion across patchy landscapes is determined by the amount and spatial patterns of suitable habitat. The initial parameters of the model were based on the natural history of the European gypsy moth (*Lymantria dispar*). The species is native to the temperate

forests of Europe and is a notorious insect defoliator, occasionally causing extensive tree mortality. A European strain was accidentally introduced to North America near Boston, USA in 1869 and has subsequently invaded much of the susceptible forest of north-eastern America (Tobin and Blackburn 2007). As part of the campaign to slow the European gypsy moth spread across the United States, intensive monitoring efforts have been focused around the invasion front. As a result, the spread of the European gypsy moth across North America is, perhaps, the most thoroughly studied biological invasion and offers unique insight into processes such as Allee effects in time and space, and comprehensive investigations of the interactions between individual movement to mate finding and links between landscape structure and movement (Tobin et al. 2015). We first tested the relative importance of the quantity of suitable habitat, its configuration, as well as their interaction, as predictors of patterns of density and rate of spread of invasive species. We then identified a generic core of landscape features that significantly affect biological invasion success. Our study proposes that change in landscape structure is an additional explanation of the highly variable spread dynamics observed in natural and anthropogenic landscapes. Consequently, a landscape-scale perspective could significantly improve spread risk assessment and the design of control or containment strategies.

Material and methods

A spatially-explicit, stochastic spread model

The central part of the modelling framework is provided by a spatially-explicit, mechanistic model, MDiG, that represents current understanding of the ecology of invasive insect spread and establishment (Pitt 2008; Pitt et al. 2009). The initial parameters of the model were based on the natural history of the European gypsy moth (*Lymantria dispar*). These parameters have been used in several studies considering European gypsy moth population dynamics and spread in complex patch-matrix landscapes (With 2002; Liebhold and Bascompte 2003; Nesslage et al. 2007), including the MDiG framework (Lustig et al. 2017). A sensitivity analysis evaluating the influence of slight changes to these base parameters was then

used to examine individual and joint effects of parameters and ranked parameters based on their influence on the dynamics of simulated spread. Therefore the range of parameters tested in the present study are not limited to the European gypsy moth but include those for other insect species and sub-species, including for example, the Asian and Japanese gypsy moths.

To initialize a simulation, individuals were located on a square lattice (simulation arena) comprised of suitable and unsuitable habitat types. Following Johnson et al. (2006) and Liebhold and Bascompte (2003), the local population density (density per raster cell) was approximated by a deterministic Allee logistic growth model:

$$N_t = N_t \exp \left[r \left(1 - \frac{N}{K} \right) \left(\frac{N_t - 1 - C}{K} \right) \right] \quad (1)$$

where C is the Allee threshold, r the intrinsic growth rate and K the carrying capacity. The values of these parameters were based on previous estimates reported in Liebhold and Bascompte (2003) and Johnson et al. (2006) from capture-release data collected from 1988 to 2004 at the invasion front (Table 1).

Spatially-explicit rules determine the pattern of local dispersal and generic long distance dispersal spread. For every occupied raster cell (or habitat patch), a proportion of the individuals spread evenly to the surrounding patches. In addition, a Poisson process is used to generate how many long distance dispersal

events originate from each habitat patch (Pitt 2008; Lustig et al. 2017). The frequency of these long-distance dispersal events correspond to the mean of the underlying Poisson distribution and was set to 0.05. The distance travelled by the individuals is approximated by a Cauchy probability distribution as it allows for long, rare dispersal distances which may occur naturally (wind dispersal for example) or which may represent human assisted dispersal (Hastings et al. 2005). Following Johnson et al. (2006), we fixed the median dispersal distances of long-distance dispersal events (median of the Cauchy distribution) at five raster cells. The direction of dispersal was sampled from a uniform distribution (Pitt 2008).

Generating and quantifying landscape heterogeneity

We generated binary (suitable, unsuitable habitat) landscape patterns for 10 km cell size raster grids of extents $1280 \times 1280 \text{ km}^2$ to approximate local movements of larvae and male adults gypsy moth (Jankovic and Petrovskii 2013). We used the computer program Qrule 4.2 (Gardner 1999) to generate a gradient of landscape complexity, in which fragmentation (measured as the degree of spatial autocorrelation) and proportion of habitat cover can be systematically and independently controlled (Gardner and Urban 2007). Qrule uses a midpoint displacement algorithm (Saupe 1988) to generate multi-fractal maps in which the

Table 1 Parameter values for the spatially-explicit, individual based model, MDiG

Parameters	Abbreviation	Parameters value
Population demography		
Growth rate	r	0.815, 1.223*, 1.63 per capacity growth
Allee threshold	C	0, 2*, 5 individuals per raster cell
Carrying capacity	K	30, 50*, 100 individuals per raster cell
Long-distance dispersal behaviour		
Median distance	λ	3, 5*, 7 raster cells
Frequency	f	0.01, 0.05*, 0.09
Landscape structure		
Landscape spatial autocorrelation (fragmentation)	H	$H = 0, 0.3, 0.5, 0.7, 0.9$
Percentage of suitable habitat patches in a binary scheme	P	$P = 5, 15, 35, 55, 75, 95$

Parameters are subdivided into the three main model ‘components’

Those parameters marked with asterisks indicate the baseline parameter values for a spread model of European gypsy moth

degree of spatial autocorrelation among adjacent cells (H) can be controlled. We generated landscape patterns in a full factorial design across a five-steps gradient in spatial autocorrelation [$H \in (0.1, 1)$ in increments of 0.2, 0 being close to random and 1 being completely clustered] and a six-steps gradient in proportion of suitable habitat cover [$P \in (5, 95\%)$ in 10% increments] with 10 replicate landscapes for each of the 35 factor combinations (Table 1; Lustig et al. 2015).

For each sample landscape, we calculated landscape metrics using the computer program FRAGSTATS (McGarigal et al. 2012). These metrics provide simple quantitative measurements of the composition and configuration of a landscape. The landscape metrics were defined for suitable habitat cover only and are commonly referred to as class-level metrics. McGarigal et al. (2012) categorized these metrics into five groups corresponding to the aspect of landscape structure emphasized. These include patch area/density/edge, shape, aggregation, contrast, core, isolation/proximity and connectivity metrics (Table 1). In addition, we included the percentage of the suitable habitat (PLAND), considered the most universal measure of landscape composition, to enable a comparison between the relative effect of landscape configuration, landscape composition and their potential interactions.

Sensitivity analysis

Insect species can be placed along a ‘slow-fast life-history continuum’, where changes in population growth rate arise mainly from variability in reproductive rates in fast species and in survival rates for slow species (Herrando-Pérez et al. 2012). The position of a species along this continuum could also reflect the propensity of a species to invade a new environment. Similarly, changes in dispersal distances, frequencies of dispersal events, carrying capacity and Allee threshold are also expected among species. We used MdiG to broadly capture this variation, by creating nine different combinations of species’ life-history attributes and dispersal abilities in a mono-factorial design (Table 1). The main reason for doing this was to evaluate how change in the intrinsic growth rate, carrying capacity, Allee effect threshold, and the frequency and median distance of long-distance dispersal events affect the dynamics of spread, and

to quantify a general relationship across life-history attributes, with changes to landscape variables. We varied each parameter over three values (Table 1) and studied the effects of these changes on the dynamics of the simulated invasion. For each landscape, we allowed the species to expand its range for 30 years, one model time step represents one year, and we replicated the simulations 25 times to account for dispersal stochasticity. We recorded four response variables over time: the population density d (number of individuals in the population), the rate of spread—ROS (number of new cells occupied per simulation run), the average dispersal distance—avDist, and the maximum dispersal distance—maxDist.

Statistical analysis

To investigate the role of landscape metrics as indicators of invasive insect spread, we used a multi-model inference framework (Burnham and Anderson 2002). A multi-model analysis provides a means to simultaneously compare multiple regression models, to evaluate how well each is supported by data, and potentially to identify the best supported model(s). This approach accounts for the uncertainty associated with a single model by providing confidence interval coverage of variable estimates. Statistical analyses were performed using the R statistical system v 3.2.2 (R Development Core Team 2013).

We used generalized linear models (GLMs) with a Gaussian error distribution. Four response variables were considered: the population density— d , the rate of spread—ROS, the average dispersal distance—avDist, and the maximum dispersal distance—maxDist, respectively. The predictor variables included 84 metrics of landscape configuration and composition (Table 1). Prior to conducting the multivariate regression, we reduced the collinearity among landscape metrics by selecting independent groups of metrics identified in Lustig et al. (2015). We further assessed the degree of multicollinearity among predictor variables in each group by calculating the generalized variance inflation factor (GVIF) for all predictors (Dormann et al. 2013). Predictors giving high GVIF were identified by calculating the pair-wise correlation between all predictors using a non-parametric Spearman’s rank correlation. We removed highly correlated variables from the analysis until all GVIF values were smaller than 10 (Table 2).

Table 2 List of landscape metrics considered as useful predictors of invasive spread

Metrics	Abbreviated code	Range	Description
Area/density/edge metrics			
Percentage of suitable habitat	PLAND	4.34 – 96.01	
Edge density	ED	3.76 – 540.04	Measure of edge length on a per unit area
Normalized shape index	nLSI	0.01 – 0.75	Measure of total length of edge normalized by the number of cell surface. It provides a simple measure of class aggregation or clumpiness
Radius of gyration distribution	GYRATE_CV	0.00 – 587.09	Measure of the variance in patch extent (mean distance each cell in the patch). It is effected by both patch size and patch compaction
Shape metrics			
Perimeter-area ration distribution	PARA_MD	79.36 – 4000.00	Median of perimeter-area ratio (simple measure of shape complexity)
Shape index distribution	SHAPE_MD	1.00 – 2.74	Measure of the overall shape complexity
Related circumscribing circle distribution	CIRCLE_AM	0.38 – 0.71	Average (AM), median (MA) and range (RA) of patch elongation
	CIRCLE_RA	0.00 – 0.87	
	CIRCLE_CV	0.00 – 151.29	
Fractal index distribution	FRAC_MD	1.00 – 1.14	Measure that reflect shape complexity (median - MD and coefficient of variation -CV of the fractal dimension) across a range of spatial scale
	FRAC_CV	0.00 – 9.19	
Aggregation metrics			
Splitting index	SPLIT	1.09 – 21343	Measure of the cumulative area distribution, SPLIT = 1 when the landscape consist of one patch and increases as the focal patch is subdivided into smaller patch
Percentage of like adjacencies	PLADJ	17.88 – 99.41	Frequency with which different pairs of patch types appear side-by-side
Contrast metrics			
Edge contrast index	ECON_RA	1.09 – 21343	Mediam (MD), standard deviation (SD) and range (RA) of the amount of contrast along the patch perimeter
	ECON_MD	32.31 – 100.00	
	ECON_SD	0.00 – 23.01	
Core metrics			
Disjunct core area density	DCAD	0.00 – 531.12	Number of disjunct core area on a per unit area basis
Core are distribution	CORE_MD	0.00 – 399.31	Median area in focal patch greater than a specified depth-of-edge distance
Disjunct core area distribution	DCORE_MD	0.00 – 482.21	Median (MD) and standard deviation (SD) area in disjunct patch greater than a specified depth-of-edge distance C
	DCORE_SD	0.00 – 180.97	
Core are index distribution	CAI_CV	0.00 – 2858.56	Coefficient of variation of patch core area as a percentage of patch area
Isolation/proximity metrics			
Proximity index distribution	PROX_AM	0.00 – 1255.84	Average (AM) and coefficient of variation (CV) o f the proximity of all patches whose edges area within a specified search radius
	PROX_CV	0.00 – 5743.96	

Table 2 continued

Metrics	Abbreviated code	Range	Description
Connectivity metrics			
Connect index	CONNECT	0.00 – 88.76	Number of functional joining between patches of the corresponding patch type
	PROX_CV	0.00 – 5743.96	

A detailed description of each metric can be found in McGarigal et al. (2012)

We then performed a multimodel regression model procedure based on the Akaike Information Criterion (AICc) with a correction for finite sample sizes (Burnham and Anderson 2002). Landscape metrics were mean-centred to facilitate the interpretation of the main effect and the outputs were log transformed to improve the normal distribution of each model's residuals. First, we identified the landscape variables that significantly improved model performance (lowest AICc values) such that they individually accounted for 95% of the cumulative sum of Akaike weights (Akaike weights represent the likelihood of a model) were retained. Second, we calculated the average parameter estimates of the model, and their 95% confidence intervals, using a model averaging algorithm. The relative importance of each landscape metric as a predictor of invasive spread was determined, based on the sum of Akaike weights, with 1 being the most important (the metric variable is present in all model candidates for each species scenario) and 0 the least important. Possible predictor variables were considered to contribute to model performance improvement if their AICc weight summation was relatively high ($w > 0.7$). Model selection for mixed models was conducted using 'lme4' package (Bates et al., 2015) and 'MuMIn' package for model-averaging of coefficients (Bartoń 2016).

Results

Aspects of landscape structure influencing the spread of invasive insects

The average population density, the rate of spread, the mean dispersal distance and the maximum dispersal distance were strongly correlated to three landscape metrics: proportion of suitable habitat in the landscape (PLAND)—the most common measure of habitat

composition; edge density (ED)—total length of borders between habitat patches in landscape, and normalized shape index (nLSI)—a simple measure of habitat patch shape and clumpiness. These three landscape metrics collectively represent a gradient from areas with few, small and clustered habitat patches towards an area with high inter-dispersion and covered by a large amount of habitat with elongated patches. The effect of the proportion of suitable habitat in the landscape (PLAND) was the most important variable affecting all aspects of spread (Table 3). Increase in density, rate of spread, mean dispersal distance and maximum dispersal distance were all positively related to proportion of suitable habitat in the landscape, while these four components of spread were negatively related to the normalized shape index. An increase in population density, rate of spread and maximum dispersal distance were positively related to edge density (ED), while average dispersal distance was negatively related to edge density.

The percentage of like adjacencies (PLADJ)—which shows the frequency with which different pairs of habitat patches appear side-by-side in the landscape, and the splitting index (SPLIT)—which characterize the disconnection between suitable habitat patches, significantly affected population density and rate of spread. In addition, the mean circumscribing circle (CIRCLE_AM)—a measure of patch elongation, the connectivity index (CONNECT), and the amount of disjunct core areas (DCDA) also had a significant effect on population density and rate of spread. Although the effects were significant, the actual effect size of the last three landscape metrics on population density were small, with lower summed Akaike weights (0.01, 0.01 and 0.02 respectively) and model partial slope coefficient near 0 (Table 3).

The core metrics, in particular, the median and standard deviation of the disjunct patch area,

Table 3 Model-average partial regression coefficient (β) and unconditional 95% coefficient intervals (CI) from models of total population density, occupied area, rate of spread, mean dispersal distance and maximum dispersal distance in relation to landscape variation

Metrics	Insect density (<i>d</i>)				Occupied area (OA)				Rate of spread (ROS)			
	w	β	Lower CI	Upper CI	w	β	Lower CI	Upper CI	w	β	Lower CI	Upper CI
PLAND	1	0.1745	0.161	0.188	1	0.018	0.0170	0.0191	1	0.2232	0.2053	0.2412
ED	0.62	0.0277	0.0146	0.0407					1	0.0279	0.0140	0.0419
nLSI	0.96	-0.0453	-0.057	-0.033	0.6	-0.001	-0.002	-0.0002	1	-0.0432	-0.0587	-0.0278
PLADJ	0.67	0.0647	0.0425	0.0869	0.4	0.001	0.0002	0.002	1	0.0488	0.0258	0.0720
SPLIT	0.59	0.0190	0.0083	0.0297					1	0.0200	0.0098	0.0303
CIRCLE_AM	0.02	0.0149	0.0033	0.0266					0.82	0.0168	0.0057	0.0278
CONNECT	0.01	-0.0099	-0.020	-0.0003					1	-0.0121	-0.0215	-0.0028
DCDA	0.08	0.0129	0.0040	0.0219					0.17	0.0118	0.0034	0.0202
PLAND:SPLIT	1	-1.0682	-1.5140	-0.6223					1	-1.3602	-1.8091	-0.9112
PLAND:CIRCLE_AM	0.08	0.0015	0.0066	0.0333					1	0.0297	0.0210	0.0385
PLAND:ED	0.04	-0.0014	-0.0456	-0.0160					1	-0.0389	-0.0508	-0.0269
PLAND:DCAD	0.03	-0.0003	-0.0212	-0.0008					0.53	0.3554	0.02603	0.6848
PLAND:PLADJ												
Metrics	Mean dispersal distance (AvDist)				Max dispersal distance (MaxDist)							
	w	β	Lower CI	Upper CI	w	β	Lower CI	Upper CI				
PLAND	1	0.0419	0.0384	0.0455	1	0.1948	0.1790	0.2106				
ED	1	-0.0028	-0.0048	-0.001	0.99	0.0222	0.0106	0.0336				
nLSI	1	-0.0084	-0.0105	-0.0064	1	-0.0486	-0.0640	-0.0333				
PLADJ					0.45	0.0288	0.0109	0.0466				
SPLIT					0.45	0.0126	0.0059	0.0193				
CIRCLE_AM					0.74	0.0138	0.0061	0.0214				
CONNECT					0.45	-0.0100	-0.0159	-0.0040				
DCDA					0.1	0.0087	0.0020	0.0153				
DCORE_MD	1	-0.0043	-0.0066	-0.002	0.85	-0.0148	-0.0226	-0.0070				
DCORE_SD	1	-0.0019	-0.0036	-0.0003								
CAI_CV					0.03	-0.0065	-0.0118	-0.0011				
SHAPE_MD					0.02	0.0046	0.0005	0.0088				
PARA_MD					0.02	-0.0045	-0.008	-0.0004				
PLAND:SPLIT	1	-0.1669	-0.2224	-0.1114	1	-1.4083	-1.8890	-0.9275				
PLAND:ED					1	-0.0395	-0.0538	-0.0252				

Table 3 continued

Metrics	Mean dispersal distance (AvDist)			Max dispersal distance (MaxDist)		
	w	β	Upper CI Lower CI	w	β	Upper CI Lower CI
PLAND:CIRCLE_AM				0.73	0.0293	0.02013 0.0386
PLAND:DCORE_SD				0.28	-0.0353	-0.0514 -0.0192
PLAND:DCORE_MD				0.18	-0.0171	-0.0318 -0.0024
PLAND: DCDA				0.01	-0.0145	-0.0251 -0.0039
PLAND:CAI_CV				0.01	0.0168	0.0039 0.0298

Coefficients are based on mean-centred data. AICc weights (w) indicate relative importance of covariate *j* based on summing weights across models were covariate *j* occurs

DCORE_MD and DCORE_SD, only showed a significant effect on the mean dispersal distance (avDist) and the maximum dispersal distance (maxDist). A number of shape metrics (FRAC_CV, SHAPE_MD, PARA_MD), core metrics (CAI_CV and DCAD) and aggregation/connectivity metrics (CONNECT and SPLIT) had a significant effect on dispersal distance. However, the effect size of these configuration metrics were relatively small as shown by lower summed Akaike weights and a model partial slope coefficient near 0 (Table 3).

Furthermore, we found significant interactions between the proportion of suitable habitat in the landscape (PLAND) and landscape configuration metrics, which were stronger and better supported for rate of spread and dispersal distances than for population density (Table 3). The average influence of the proportion of suitable habitat (PLAND) on rate of spread, dispersal distance and population density decreased when the degree of fragmentation in the landscape (SPLIT) and edge density (ED) increased. In contrast, the average influence of the proportion of high-quality habitat (PLAND) on rate of spread and dispersal distances was enhanced when the related circumscribing circle (CIRCLE_AM)—a measure of patch elongation, increased. These interactions predicted that the marginal increase of the proportion of suitable habitat within a landscape is on average less when the habitat is highly fragmented.

We also found significant effects of the interactions between the proportion of high-quality habitat (PLAND) and core metrics (DCORE_MD, DCORE_SD, CAI_CV and DCAD) on the maximum dispersal distance, and between the proportion of high-quality habitat (PLAND) and measure of patch aggregation (PLADJ) on the rate of spread. However, the effect of these latter interactions were relatively weak, with lower summed Akaike weights (Table 3).

Balancing effectiveness of spread and invasion success

When an Allee effect was absent, an increase in the proportion of suitable habitat (PLAND) resulted to an increase in the mean dispersal distances, and subsequently to an increase in the rate of spread and population density (Fig. 1).

In the presence of an Allee effect, the range of dispersal distances that allow for optimal spread was

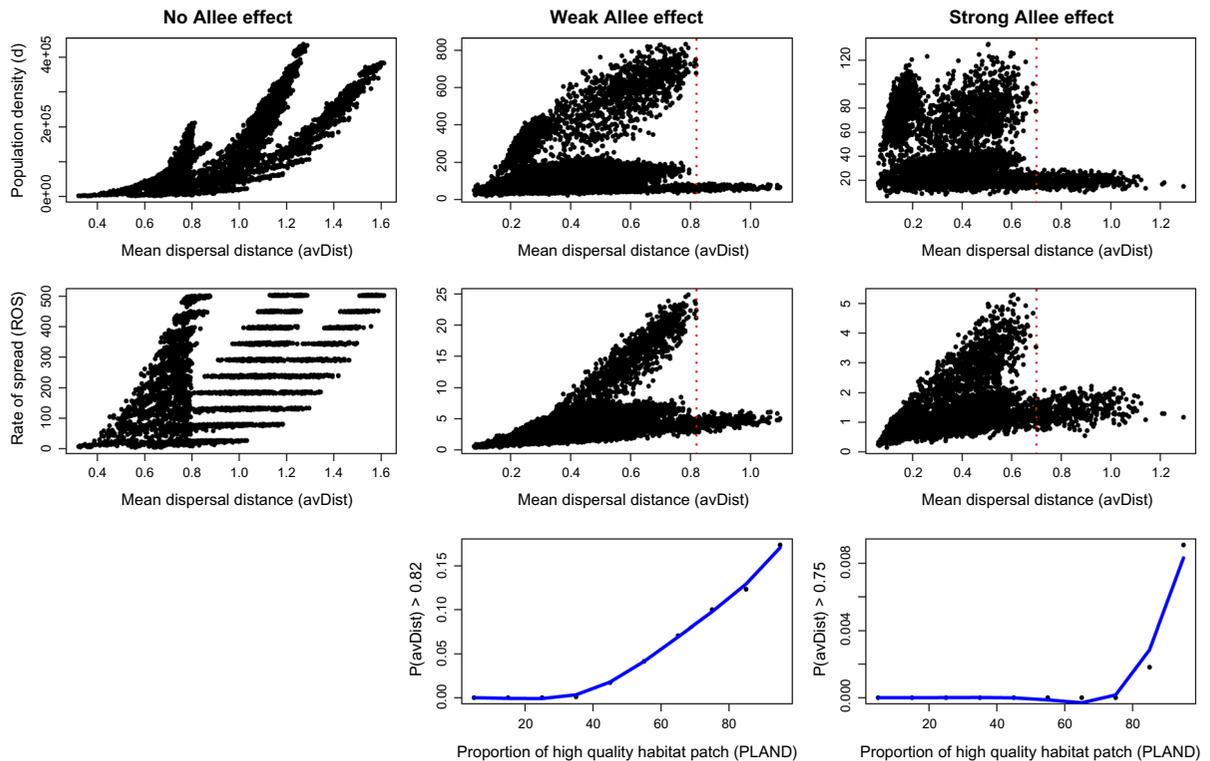


Fig. 1 Balancing effectiveness of spread and invasion success in heterogeneous landscapes. Results are shown for all parameter values tested. The top panels show how population density (d) and rate of spread (ROS) respond to different ranges of mean dispersal distances for three different scenarios: without Allee effect, with weak Allee effect and with strong Allee effect.

considerably reduced compared to the case without an Allee effect. At lower realised mean dispersal distances (avDist), spread was limited as evidenced by a lower realized mean rate of spread, but population density increased as indicated by a local maxima in the population density curve at an average mean dispersal of 0.2 m (Fig. 1). A two-fold increase in the mean dispersal distance leads to the highest rate of spread and population density. The range of permissible rate of spread and population density was dramatically reduced when the mean dispersal distance went over a certain dispersal threshold (Fig. 1). These results suggested that invasive insect species subjected to an Allee effect may present two different growth patterns when arriving to a new environment. On one hand, species that have limited dispersal abilities will maximise their populations locally but will fail to establish a population over a large area. On the other

Above a dispersal threshold (red dotted line), growth and rate of spread were considerably reduced or not observed. The bottom panel represents the probability of observing a mean dispersal distance higher than the dispersal threshold that can limit growth and spread as a function of the proportion of suitable habitat (PLAND)

hand, species that have high dispersal abilities may spread but face the added risk of not establishing or going extinct.

The results also showed that an increase in the proportion of suitable habitat (PLAND) in the landscape resulted in an increase in the probability of observing a mean dispersal distance higher than the dispersal threshold that can limit growth and spread (Fig. 1). In a landscape with more than 70% of suitable habitat, 5% of the simulations resulted in a mean dispersal distance higher than the dispersal threshold. In a landscape with more than 80% of suitable habitat, 10% of the simulations resulted in a mean dispersal distance higher than this dispersal threshold. Although a high proportion of suitable habitat would lead to more successful spread (highest mean dispersal distances) when the source population density is high enough, it may also reduce spread

success and population growth when the source population is too small. This result provides new insights into the proportion of suitable habitat as an additional explanation to the highly variable spread rate observed in both natural and anthropogenic landscapes.

Discussion

The influence of landscape structure on the spread of invasive insect species is generally acknowledged but is often difficult to quantify. In this study, we investigated the effect of landscape structure as a predictor of patterns of spread using the European gypsy moth as a model invasive insect species. We found that both landscape composition and landscape configuration influenced population density and rate of spread in significant and sometimes interactive ways.

Landscape metrics as indicators of spread

We showed that the density and rate of spread of invasive insects are more impacted by the proportion of suitable habitat in the landscape than by habitat configuration. This has significant implications for the prediction and management of invasive insect species in general. In all species scenarios studied here, the increase in density and rate of spread of the species was positively related to an increasing proportion of suitable habitat in the landscape. The direct effect of the amount of suitable habitat on invasive insect species density and spread has been reported in several studies, particularly in agroecosystems (Chaplin-Kramer et al. 2011). Our results suggest that such an effect may be caused by a greater aggregation of suitable habitat patches (as measured by nLSI, PLADJ, SPLIT) and a slight decrease in edge density. Different spread rates in different landscapes can also be caused by variation in connectivity of habitat patches, in habitat patch elongation and by variation in the ratio of edge-to-interior habitat. In other words, landscapes containing larger patches of suitable habitat with simple, circular or square shape are expected to be more conducive to the rapid spread of invasive insects. Previous research also confirms that the metrics identified in this study that characterize habitat density (With 2002; Sebert-Cuvillier et al. 2008; Tschardt et al. 2012), connectivity [e.g. (With

2002; Sebert-Cuvillier et al. 2008; Wang et al. 2011; Morel-Journel et al. 2015)], path aggregation (With and King 1999b; Wang et al. 2011) and edge density (Radeloff et al. 2000; With 2002; Tschardt et al. 2012) are important aspects of the landscape that can either influence or exacerbate the spread of insects.

Overall, we found that the main effect of the configuration of habitats at a landscape scale had less impact on total density and rate of spread of the invasive insect species when compared to the main effect of the amount of habitat. Such a finding is consistent with and confirms the finding of many studies that habitat homogenisation is one of the key drivers of global increase in pest and disease establishment and spread (Jonsson et al. 2015). Nevertheless, we recognized that population density and rate of spread of invasive insect species can be significantly affected by complex interactions between the composition and configuration of the landscape in the introduction area.

Fragmentation versus proportion of suitable habitat in the landscape

We showed that the variation in density and spread of invasive insects was best explained by an interaction between the proportion of suitable habitat in the landscape (PLAND) and the splitting index. Moreover, we found evidence of a significant interaction between the proportion of suitable habitat in the landscape and respectively, the effects of edge density and average patch elongation on rate of spread and dispersal distances.

Habitat split is a measure of habitat fragmentation designed to quantify the extent to which habitat patches are disconnected in space (Jaeger 2000). Our results contrast with theoretical studies that suggest that suitable habitat connectivity at the introduction site is a determining factor of patterns of spread (Morel-Journel et al. 2015). On the contrary, we found that invasive spread might be limited more by the size and distribution of non-habitat gaps than by a measure of habitat connectivity (rate of movement between habitat patches). Ultimately, the notion of patch aggregation is embedded within the notion of connectivity such that, when habitat split decreases, connectivity also increases. Our results are in agreement with the results of With and King (1999a) and Wang et al. (2011) who also highlighted the critical role of non-habitat gaps in reducing the spread of species over the landscape.

On the other hand, the effect of edge density and habitat patch elongation was particularly challenging to assess. In this study, a decrease in edge density led to an increase in population density and rate of spread of the gypsy moth, but a slight decrease in density. Other studies have found that depending on whether species are moving primarily within or between habitat types, the micro-environments between habitat fragments may critically increase (Radeloff et al. 2000; With 2002; Tscharntke et al. 2012) or decrease (Tscharntke et al. 2012) the potential of spread. Ewers et al. (2007) further demonstrated that an increase in habitat shape complexity is associated with an increase in the amount of edge habitat that results in a higher edge density. Large patches are more likely to be of a complex shape. We found that as shape complexity increases, patches become less circular, and the probability of population increase and spread of an invasive insect species decreases.

Overall, the results demonstrated that population increase and spread of invasive insect species can be significantly affected by the combined landscape based components: suitable habitat amount, habitat patch aggregation and habitat shape complexity. We found that population density and rate of spread were positively correlated with landscape metrics that increase with decreasing habitat fragmentation, and negatively correlated with metrics which increase with increasing habitat fragmentation. To our knowledge, most theoretical studies that have focused on the spread of invasive insect species at the colonization front have also found a non-negligible effect of the spatial arrangement of habitat on local density and rate of spread (With 2002; Morel-Journel et al. 2015). However, Fahrig et al. (2011) and Tscharntke et al. (2012) proposed that species respond idiosyncratically to habitat fragmentation versus habitat loss, which may suggest that highly mobile species can tolerate habitat fragmentation as long as the amount of total habitat is sufficient. Their finding suggests that the configuration of the landscape might not always be important for predicting the density and rate of spread of invasive insect species.

Impact of landscape structure on population dynamics

Clearly, the overall outcome of spread critically depends on several life-history characteristics and species dispersal ability as well as landscape factors.

As reflected by Fig. 1, our results support two important hypothesis about population spread and growth in a heterogeneous environment. First, in the absence of an Allee effect, and in the absence of other influences (predation, for example), a population can spread and grow regardless of the proportion of suitable habitat. Increasing the proportion of suitable habitat in the landscape increases the overall population density and rate of spread exponentially (Fig. 1; Shigesada and Kawasaki (1997)) Second, in the presence of an Allee effect, a population experiences a balancing effect between the effectiveness of spread and the establishment of a persistent population (Fig. 1; Smith et al. (2014)): population growth and spread are maximized at intermediate dispersal abilities but inhibited at high dispersal abilities. Species that have a high intrinsic rate of increase quickly exceed the size of population that is vulnerable to Allee effects, ensuring a higher probability of persistence of the introduced propagule(s) (Morel-Journel et al. 2015).

Furthermore, Smith et al. (2014) used a programmed Allee effect in bacteria to demonstrate that an increase in the number of suitable habitat patches can result in more prolific spread but simultaneously increases the chances that each population could fail to establish due to Allee effect. Our simulations based on insect life-history parameters are in broad agreement with these results. We found evidence of a dispersal threshold above which population spread and growth can be inhibited. Additionally, the results of this study echo the ‘all or nothing’ strategy proposed by Heimpel and Asplen (2011) and Morel-Journel et al. (2015), where they propose that a population would either go extinct quickly or form a stable population expanding across highly connected landscape. Therefore, species with an Allee effect follow idiosyncratic dynamics of spread that can be significantly affected by the structure of the landscape. This study further revealed that by either allowing or preventing the dispersal of a species from the introduction site (or effective containment) complex interactions between the composition or configuration of the landscape may push these species into a range of dispersal that allows optimal spread and growth. Specifically, the results in this study showed that in a landscape with more than 70% of suitable habitat, 5% of the simulations resulted in a mean dispersal distance higher than a dispersal threshold that can limit growth and spread. Such an

observation may offer an additional explanation to the highly variable spread dynamics observed in both natural and anthropogenic landscapes. It can also explain why, during the early stages of an outbreak or incursion, spread can be initially slow manifesting itself as a time lag followed by an increase over time. Species must establish a population density that can exceed the size vulnerable to Allee effects before effective spread will occur.

There is a lively current debate about the importance of investing pest-management resources into reducing habitat quality to limit the dispersal abilities of an invasive organism, for example by decreasing the extent of suitable habitat or managing the spatial aggregation of habitat patches across the landscape (With 2004). Such habitat manipulation is consistent with the management practice of creating “barrier zones” at invasion fronts where suppression activities (poisoning/trapping) are employed to create areas of fragmented habitat that disrupt the movement of organisms across the landscape and slow the rate of expansion. Indeed, such a technique was used by the U.S Forest Service to control the spread of the European gypsy moth across North America (Sharov and Liebhold 1998; With 2004). However, Nessler et al. (2007) reported a lack of a typical threshold response to a declining proportion of habitat, using empirical data on the European gypsy moth invasion wave front across Michigan (1985–1996). Nessler et al. (2007) further suggested that the concept of creating areas of fragmented habitat as “barrier zones” to slow the invasion wavefront may be of limited use for good dispersers like the European gypsy moth. Using simulation models in this present study, we also found that the rate of spread and population density of several invasive insect species did not exhibit a typical threshold response to declining proportion of habitat. Instead, in situations where the proportion of suitable habitat in the landscape is already above a critical threshold for species dispersal and persistence, our results suggested that further manipulation of the habitat may push these species into a range of dispersal that allows optimal spread. In addition, we found dispersers are likely to be influenced not only by the proportion of habitat in the landscape but also by the spatial aggregation and structural connectivity of habitat patches. Such results create challenges for designing management strategies focused on reducing the spread of invasive insects but

that also work across species with very different behaviours and in different landscapes. This is because the degree of habitat fragmentation and the proportion of habitat in the landscape can have very different impacts depending on the dispersal behaviour of the species.

Conclusion

This study offers new insights for management programs that aim to either eradicate or in the case that strategy fails, limit or contain the spread of an invasive insect species. Strong evidence was found for landscape composition and configuration shaping the successful establishment and rate of spread of a species. Adopting a strategy that systematically reduces the dispersal ability of a new introduced species by reducing dispersal between suitable habitat patches, for example (Brown et al. 2006), might inadvertently help them thrive by pushing the species into a range of dispersal that allows optimal spread and growth. We therefore recommend that management strategies for containment or eradication of invasive insect species set spatial priorities of control at the landscape scale. These spatial priorities should account for specific landscape characteristics, the stage of the invasion and the life-history characteristics of the species. The analysis in this study provides a basis for the development of a core set of structural landscape metrics as indicators of invasive insect spread. However, optimal choice of metrics will require case specific exploration of their indicator values as there is no one-case-fits-all strategy that can ensure optimal risk assessment and management control for all species and landscapes.

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